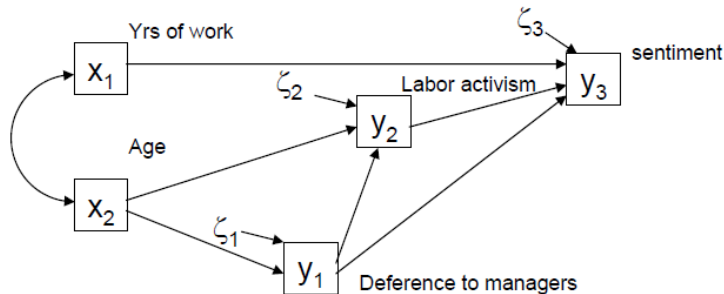


Confirmatory Factor Analysis & Structural Equation Models

Lecture 1: Overview & Path Analysis

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SCS Short Course, May, 2019



Overview

Course overview

Course notes & other materials will be available at:

<http://datavis.ca/courses/CFA-SEM>

- Lecture 1: Setting the stage: EFA, CFA, SEM, Path analysis
 - Goal: Understand relations among a large number of observed variables
 - Goal: Extend regression methods to (a) multiple outcomes, (b) latent variables, (c) accounting for measurement error or unreliability
 - Thinking: Equations → Path diagram → estimate, test, visualize
- Lecture 2: Measurement models & CFA
 - Effects of measurement error
 - Testing equivalence of measures with CFA
 - Multi-factor, higher-order models
- Lecture 3: SEM with latent variables

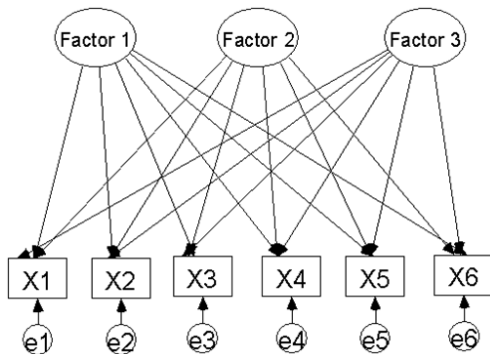
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Overview

EFA, CFA, SEM?

Exploratory Factor Analysis (EFA)

- Method for “explaining” correlations of observed variables in terms of a small number of “common factors”
- Primary Q: How many factors are needed?
- Secondary Q: How to interpret the factors?

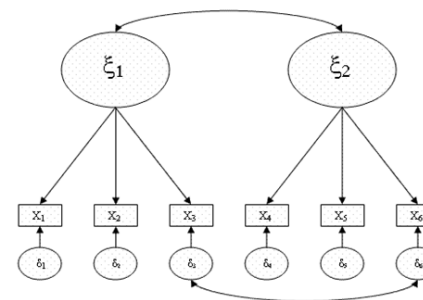


Three-factor EFA model. Each variable loads on all factors. The factors are assumed to be uncorrelated

EFA, CFA, SEM?

Confirmatory Factor Analysis (CFA)

- Method for **testing hypotheses** about relationships among observed variables
- Does this by imposing restrictions on an EFA model
- Q: Do the variables have a given factor structure?
- Q: How to compare competing models?



Two-factor CFA model with non-overlapping factors. The factors are allowed to be correlated, as are two unique factors

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EFA, CFA, SEM?

Structural Equation Models (SEM)

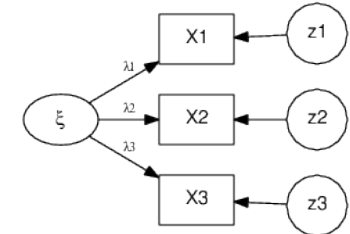
- Generalizes EFA, CFA to include
 - Simple and multiple regression
 - General linear model (Anova, multivariate regression, ...)
 - Path analysis — several simultaneous regression models
 - Higher-order CFA models
 - Multi-sample CFA models ("factorial invariance")
 - Latent growth/trajectory models
 - Many more ...
- A general framework for describing, estimating and testing linear statistical models

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Recall basic EFA ideas

- Observed variables, x_1, x_2, \dots, x_p is considered to arise as a set of regressions on some **unobserved, latent variables** called **common factors**, $\xi_1, \xi_2, \dots, \xi_k$.
- That is, each variable can be expressed as a regression on the common factors. For three variables and one common factor, ξ , the model is:

$$\begin{aligned} x_1 &= \lambda_1 \xi + z_1 \\ x_2 &= \lambda_2 \xi + z_2 \\ x_3 &= \lambda_3 \xi + z_3 \end{aligned}$$



- The **common factors** account for correlations among the x s.
- The z_i are error terms, or **unique factors**

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The EFA model

- For k common factors, the common factor model is

$$\begin{aligned} x_1 &= \lambda_{11}\xi_1 + \dots + \lambda_{1k}\xi_k + z_1 \\ x_2 &= \lambda_{21}\xi_1 + \dots + \lambda_{2k}\xi_k + z_2 \\ &\vdots \\ x_p &= \lambda_{p1}\xi_1 + \dots + \lambda_{pk}\xi_k + z_p \end{aligned}$$

$$\begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_p \end{bmatrix} = \begin{bmatrix} \lambda_{11} & \dots & \lambda_{1k} \\ \lambda_{21} & \dots & \lambda_{2k} \\ \vdots & & \vdots \\ \lambda_{p1} & \dots & \lambda_{pk} \end{bmatrix} \begin{bmatrix} \xi_1 \\ \vdots \\ \xi_k \end{bmatrix} + \begin{bmatrix} z_1 \\ z_2 \\ \vdots \\ z_p \end{bmatrix}$$

$$\mathbf{x} = \mathbf{\Lambda}\boldsymbol{\xi} + \mathbf{z}$$

- This looks like a set of multiple regression models for the x s, but it is **not testable**, because the factors, ξ , are unobserved

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The EFA model

- However, the EFA model implies a particular form for the variance-covariance matrix, Σ , which **is testable**

$$\mathbf{x} = \mathbf{\Lambda}\boldsymbol{\xi} + \mathbf{z} \quad \longrightarrow \quad \Sigma = \mathbf{\Lambda}\Phi\mathbf{\Lambda}^T + \Psi$$

where:

- $\mathbf{\Lambda}_{p \times k}$ = factor pattern ("loadings")
- $\Phi_{k \times k}$ = matrix of correlations among factors.
- Ψ = diagonal matrix of unique variances of observed variables.
- Typically, it is initially assumed that factors are uncorrelated ($\Phi = I$, the identity matrix)
- Can use an oblique rotation to allow correlated factors

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Limitations of EFA

- The only true **statistical tests** in EFA are tests for the number of common factors (when estimated by ML)

$$H_0 : k = k_0 \quad k_0 \text{ factors are sufficient}$$

$$H_a : k > k_0 \quad > k_0 \text{ factors are necessary}$$

- Substantive questions** about the nature of factors can only be addressed approximately through factor rotation methods
 - Varimax & friends attempt rotation to **simple structure**
 - Oblique rotation methods allow factors to be correlated
 - Procrustes rotation allows rotation to a “target” (hypothesized) loading matrix

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Historical development: EFA → CFA

- ML estimation for the EFA model finds estimates that minimize the difference between the observed covariance matrix, \mathbf{S} , and that reproduced by the model, $\hat{\Sigma} = \hat{\Lambda}\hat{\Phi}\hat{\Lambda}^T + \hat{\Psi}$

- Requires imposing k^2 restrictions for a unique solution
- Gives a χ^2 test for goodness of fit

$$(N-1)F_{min}(\mathbf{S}, \hat{\Sigma}) \sim \chi^2 \quad \text{with } df = [(p-k)^2 - p - k]/2$$

- Joreskog (1969) proposed that a factor hypothesis could be tested by imposing restrictions on the EFA model—fixed elements in Λ , Ψ , usually 0
 - Needs more than k^2 restrictions
 - The ML solution is then found for the remaining **free parameters**
 - The χ^2 for the restricted solution gives a test for how well the hypothesized factor structure fits.

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CFA: Restricted EFA

The pattern below specifies two non-overlapping oblique factors. The **x**'s are the only free parameters.

$$\Lambda = \begin{bmatrix} x & 0 \\ x & 0 \\ x & 0 \\ 0 & x \\ 0 & x \\ 0 & x \end{bmatrix} \quad \Phi = \begin{bmatrix} 1 & \\ x & 1 \end{bmatrix}$$

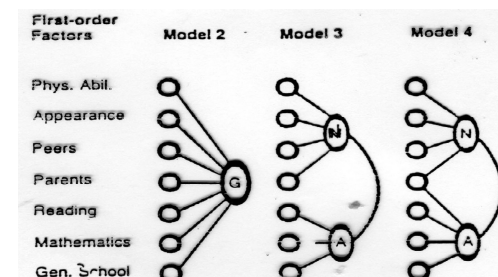
- This CFA model has only 7 free parameters and $df = 15 - 7 = 8$.
- A $k = 2$ -factor EFA model would have all parameters free and $df = 15 - 11 = 4$ degrees of freedom.
- If this restricted model fits (has a small χ^2/df), it is strong evidence for two non-overlapping oblique factors.
- That hypothesis cannot be tested by EFA + rotation.

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Historical development: CFA → SEM

Higher-order factor analysis: The ACOVS model

- With more than a few factors, allowed to be correlated ($\Phi \neq I$), can we factor the **factor** correlations?
- In EFA, this was done by another EFA of the estimated factor correlations from an oblique rotation
- The second stage of development of CFA/SEM models combined these steps into a single model, and allowed different hypotheses to be compared



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LISREL/SEM Model

- Jöreskog (1973) further generalized the ACOVS model to include structural equation models along with CFA.
- Two parts:
 - **Measurement model** — How the latent variables are measured in terms of the observed variables; measurement properties (reliability, validity) of observed variables. [Traditional factor analysis models]
 - **Structural equation model** — Specifies causal relations among observed and latent variables.
 - Endogenous variables - determined within the model (y)
 - Exogenous variables - determined outside the model (x)

Measurement models
for observed variables

$$x = \Lambda_x \xi + \delta$$

$$y = \Lambda_y \eta + \epsilon$$

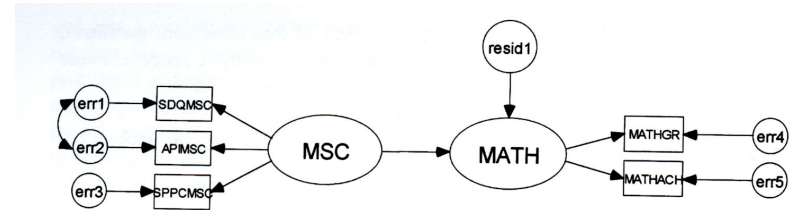
Structural eqn. for latent
variables

$$\eta = B\eta + \Gamma\xi + \zeta$$

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LISREL/SEM Model

SEM model for measures of Math Self-Concept and MATH achievement:



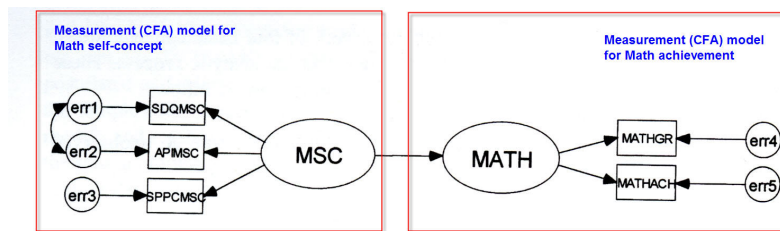
This model has:

- 3 observed indicators in a measurement model for MSC (x)
- 2 observed indicators in a measurement model for MATH achievement (y)
- A structural equation predicting MATH achievement from MSC

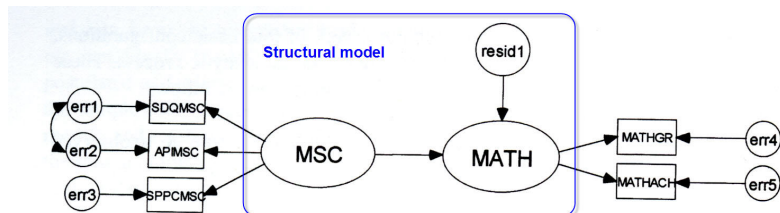
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LISREL/SEM Model

Measurement sub-models for x and y



Structural model, relating ξ to η

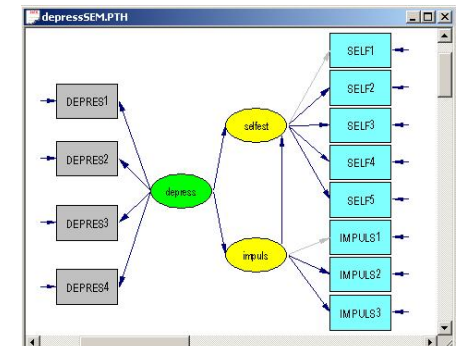
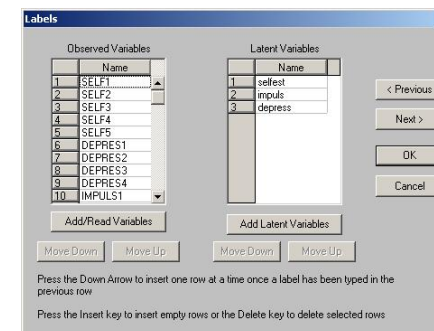


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CFA/SEM software: LISREL

LISREL (<http://www.ssicentral.com/>) [student edition available]

- Originally designed as stand-alone program with matrix syntax
- LISREL 8.5+ for Windows/Mac: includes
 - interactive, menu-driven version;
 - PRELIS (pre-processing, correlations and models for categorical variables);
 - SIMPLIS (simplified, linear equation syntax)
 - path diagrams from the fitted model

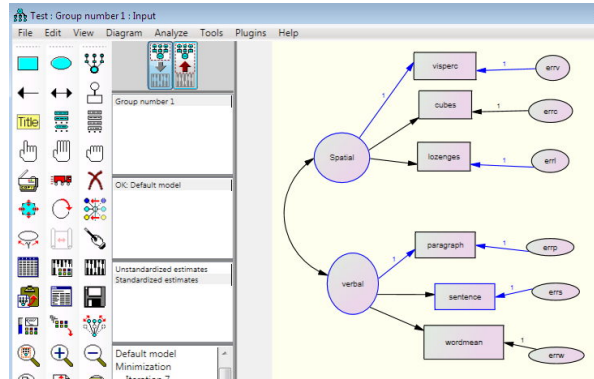


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CFA/SEM software: Amos

Amos (www.ibm.com/software/products/en/spss-amos): Linear equation syntax + path diagram model description

- import data from SPSS, Excel, etc; works well with SPSS
- Create the model by drawing a path diagram
- simple facilities for multi-sample analyses
- nice comparative displays of multiple models



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SAS: PROC CALIS

- SAS 9.3+: PROC CALIS
 - MATRIX (à la LISREL), LINEQS (à la EQS), RAM, ... syntax
 - Now handles multi-sample analyses
 - Multiple-model analysis syntax, e.g., Model 2 is like Model 1 except ...
 - Enhanced output controls
 - customizable fit summary table
- SAS macros <http://datavis.ca/sasmac/>:
 - `caliscmp` macro: compare model fits from PROC CALIS à la Amos
 - `csmppower` macro: power estimation for covariance structure models

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R: sem, lavaan and others

- `sem` package (John Fox)
 - flexible ways to specify models: `cfa()`, `linearEquations()`, and `multigroupModel()`
 - `bootSem()` provides bootstrap analysis of SEM models
 - `miSem()` provides multiple imputation
 - path diagrams using `pathDiagram()` → `graphviz`
 - `polychor` package for polychoric correlations
- `lavaan` package (Yves Rosseel)
 - Functions `lavaan()`, `cfa()`, `sem()`, `growth()` (growth curve models)
 - Handles multiple groups models
 - `semTools` provides tests of measurement invariance, multiple imputation, bootstrap analysis, power analysis for RMSEA, ...
- `semPlot` package — path diagrams for `sem`, `lavaan`, `Mplus`, ... models

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Mplus

Mplus <https://www.statmodel.com/> [\$\$\$, but cheaper student price]

- Handles the widest range of models: CFA, SEM, multi-group, multi-level, latent group
- Variables: continuous, censored, binary, ordered categorical (ordinal), unordered categorical (nominal), counts, or combinations of these variable types
- For binary and categorical outcomes: probit, logistic regression, or multinomial logistic regression models.
- For count outcomes: Poisson and negative binomial regression models.
- Extensive facilities for simulation studies.

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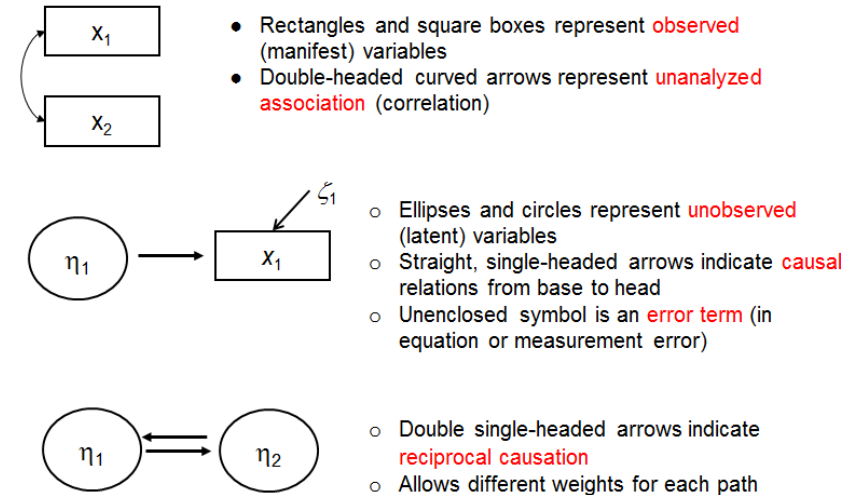
Caveats

- CFA and SEM models are fit using the covariance matrix (\mathbf{S})
 - The raw data is often not analyzed
 - Graphs that can reveal potential problems often not made
- Typically, this assumes all variables are **complete, continuous, multivariate normal**. Implies:
 - \mathbf{S} is a sufficient statistical summary
 - Relations assumed to be linear are in fact linear
 - Goodness-of-fit (χ^2) and other tests based on asymptotic theory ($N \rightarrow \infty$)
 - Missing data, skewed or long-tailed variables must be handled first
- Topics not covered here:
 - Using polychoric correlations for categorical indicators
 - Distribution-free estimation methods (still asymptotic)
 - Bootstrap methods to correct for some of the above
 - Multiple imputation to handle missing data

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Path diagrams: Symbols

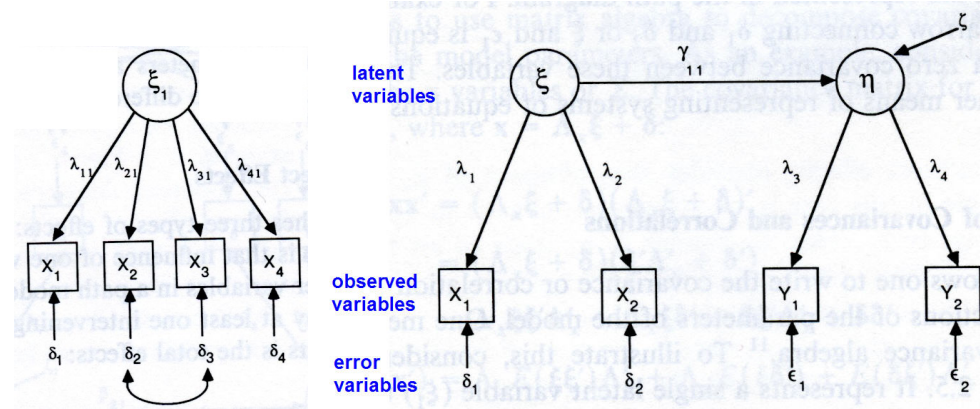
Visual representation of a set of simultaneous equations for EFA, CFA, SEM models (idea from Sewall Wright, 1920s)



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Path diagrams

Schematic Examples:

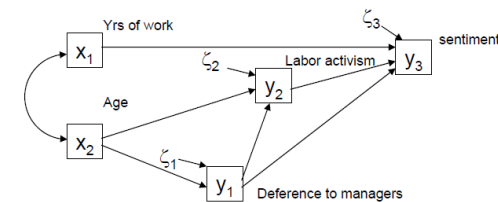


CFA, 1-factor model
(correlated errors)

SEM, two latent variables, each with two indicators
Causal relation between ξ (Xs) and η (Ys)

Path diagrams

Substantive example: Path analysis model for union sentiment (McDonald & Clelland, 1984)



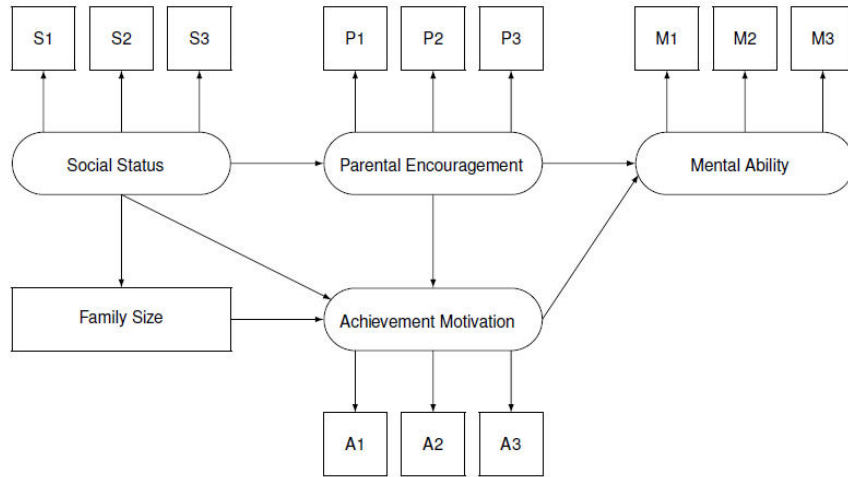
- No latent variables— all variables are observed indicators
- x_1, x_2 are **exogenous** variables— they **are not explained** within the model
- Correlation between x_1, x_2 is shown as a double-headed arrow
- y_1, y_2, y_3 are **endogenous** variables— they **are explained** within the model
- Causal relations are shown among the variables by single-headed arrows
- Residual (error) terms, $\zeta_1, \zeta_2, \zeta_3$ are shown as single-headed arrows to the y variables

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Path diagrams

Substantive example: SEM with multiple indicators, path model for latent variables (error terms not shown)



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Path Analysis

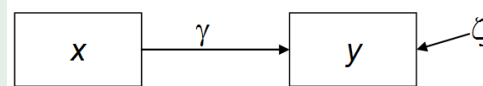
- Path analysis is a simple special case of SEM
 - These models contain only **observed** (manifest) variables,
 - No **latent** variables
 - Assumes that all variables are measured **without error**
 - The only error terms are residuals for y (endogenous) variables
- They are comprised of a set of **linear regression models**, estimated **simultaneously**
 - Traditional approaches using MRA fit a collection of **separate** models
 - Multivariate MRA (MMRA) usually has **all** y variables predicted by **all** x variables
 - In contrast, SEM path models allow a more general approach, in a single model

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Path Analysis: Simple examples

Simple linear regression

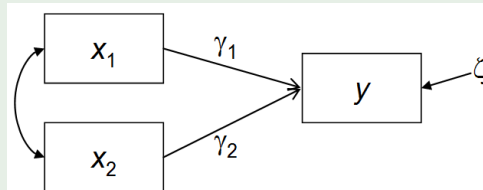
$$y_i = \gamma x_i + \zeta_i$$



- γ is the slope coefficient; ζ is the residual (error term)
- Means and regression intercepts usually not of interest, and suppressed

Multiple regression

$$y_i = \gamma_1 x_{1i} + \gamma_2 x_{2i} + \zeta_i$$



- Double-headed arrow signifies the assumed correlation between x_1 & x_2
- In univariate MRA ($y \sim x_1 + \dots$), there can be any number of x s

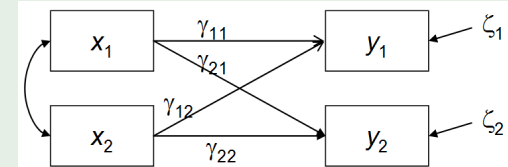
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Path Analysis: Simple examples

Multivariate multiple regression

$$y_{1i} = \gamma_{11}x_{1i} + \gamma_{12}x_{2i} + \zeta_{1i}$$

$$y_{2i} = \gamma_{21}x_{1i} + \gamma_{22}x_{2i} + \zeta_{2i}$$



- Now need two equations to specify the model
- Note subscripts: γ_{12} is coeff of y_1 on x_2 ; γ_{21} is coeff of y_2 on x_1

With more equations and more variables, easier with vectors/matrices

$$\begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \begin{bmatrix} \gamma_{11} & \gamma_{12} \\ \gamma_{21} & \gamma_{22} \end{bmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} + \begin{pmatrix} \zeta_1 \\ \zeta_2 \end{pmatrix} \quad \text{or} \quad \mathbf{y} = \mathbf{\Gamma} \mathbf{x} + \mathbf{\zeta}$$

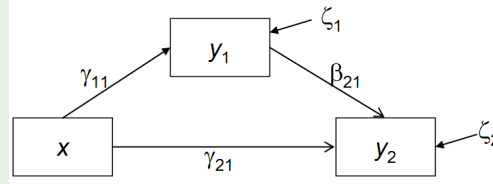
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Path Analysis: Simple examples

Simple mediation model

$$y_{1i} = \gamma_{11}x_i + \zeta_{1i}$$

$$y_{2i} = \gamma_{21}x_i + \beta_{21}y_{1i} + \zeta_{2i}$$



- Something new: y_1 is a dependent variable in the first equation, but a predictor in the second
- This cannot be done **simultaneously** via standard MRA or MMRA models

$$\begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \begin{bmatrix} 0 & 0 \\ \beta_{21} & 0 \end{bmatrix} \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} + \begin{pmatrix} \gamma_{11} \\ \gamma_{21} \end{pmatrix} x + \begin{pmatrix} \zeta_1 \\ \zeta_2 \end{pmatrix} \quad \text{or} \quad \mathbf{y} = \mathbf{B}\mathbf{y} + \mathbf{\Gamma}\mathbf{x} + \boldsymbol{\zeta}$$

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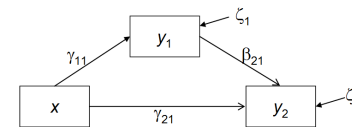
Exogenous and Endogenous Variables

Exogenous variables

- Are only **independent** (x) variables in the linear equations
- Never have arrows pointing at them from other variables
- They are determined **outside** ("ex") the model
- In path analysis models they are considered measured w/o error

Endogenous variables

- Serves as a **dependent** variable (outcome) in at least one equation
- If a variable has at least one arrow pointing to it, it is endogenous
- They are determined **inside** ("en") the model
- In path analysis models they always have error terms



In the simple mediation model, x is exogenous, and y_1, y_2 are endogenous

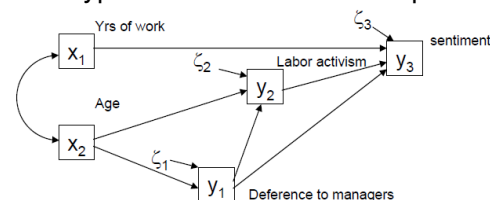
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Example: Union sentiment

Norma Rae example— Union sentiment among non-union Southern textile workers (McDonald & Clelland (1984); Bollen (1986))

- Exogenous variables: x_1 (years of work); x_2 (age)
- Endogenous variables: y_1 (deference to managers); y_2 (support for labor activism); y_3 (support for unions)

The hypothesized model is comprised of three linear regressions



$$y_1 = \gamma_{12}x_2 + \zeta_1$$

$$y_2 = \beta_{21}y_1 + \gamma_{22}x_2 + \zeta_2$$

$$y_3 = \beta_{31}y_1 + \beta_{32}y_2 + \gamma_{31}x_1 + \gamma_{32}x_2 + \zeta_3$$

These can be expressed as a single matrix equation for the \mathbf{y} variables:

$$\begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ \beta_{21} & 0 & 0 \\ \beta_{31} & \beta_{32} & 0 \end{bmatrix} \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix} + \begin{bmatrix} 0 & \gamma_{12} \\ 0 & \gamma_{22} \\ \gamma_{31} & 0 \end{bmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} + \begin{pmatrix} \zeta_1 \\ \zeta_2 \\ \zeta_3 \end{pmatrix}$$

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The general path analysis model

The general form of a SEM path analysis model is expressed in the matrix equation

$$\mathbf{y} = \mathbf{B}\mathbf{y} + \mathbf{\Gamma}\mathbf{x} + \boldsymbol{\zeta}$$

where:

- \mathbf{y} is a $p \times 1$ vector of **endogenous** variables
- \mathbf{x} is a $q \times 1$ vector of **exogenous** variables
- $\mathbf{B}_{p \times p}$ ("Beta") gives the regression coefficients of endogenous (\mathbf{y}) variables on other endogenous variables
- $\mathbf{\Gamma}_{p \times q}$ ("Gamma") gives the regression coefficients of endogenous variables on the exogenous variables (\mathbf{x})
- $\boldsymbol{\zeta}_{p \times 1}$ is the vector of errors in the equations (i.e., regression residuals)

However, some parameters in \mathbf{B} and $\mathbf{\Gamma}$ are typically **fixed** to 0

$$\mathbf{B} = \begin{bmatrix} 0 & 0 & 0 \\ \beta_{21} & 0 & 0 \\ \beta_{31} & \beta_{32} & 0 \end{bmatrix} \quad \mathbf{\Gamma} = \begin{bmatrix} 0 & \gamma_{12} \\ 0 & \gamma_{22} \\ \gamma_{31} & 0 \end{bmatrix}$$

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The general path analysis model

Other parameters pertain to variances and covariances of the exogenous variables and the error terms

- $\Phi_{q \times q}$ ("Phi")— variance-covariance matrix of the exogenous variables. Typically, these are all **free** parameters. For the union sentiment example, Φ is a 2×2 matrix:

$$\Phi = \begin{bmatrix} \text{var}(x_1) & \text{cov}(x_1, x_2) \\ \text{cov}(x_1, x_2) & \text{var}(x_2) \end{bmatrix}$$

- $\Psi_{p \times p}$ ("Psi")— variance-covariance matrix of the error terms (ζ). Typically, the error variances are **free** parameters, but their covariances are **fixed** to 0 (models can allow correlated errors) For the union sentiment example, Ψ is a 3×3 diagonal matrix:

$$\Psi = \begin{bmatrix} \text{var}(\zeta_1) & 0 & 0 \\ 0 & \text{var}(\zeta_2) & 0 \\ 0 & 0 & \text{var}(\zeta_3) \end{bmatrix}$$

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Union sentiment: using the sem package

Read the variance-covariance matrix of the variables using **readMoments()**

```
library(sem)
union <- readMoments(diag=TRUE,
  names=c('y1', 'y2', 'y3', 'x1', 'x2'),
  text="
14.610
-5.250 11.017
-8.057 11.087 31.971
-0.482 0.677 1.559 1.021
-18.857 17.861 28.250 7.139 215.662
")
```

The model can be specified in different, equivalent notations, but the simplest is often linear equations format, with **specifyEquations()**

```
union.mod <- specifyEquations(covs="x1, x2", text="
y1 = gam12*x2
y2 = beta21*y1 + gam22*x2
y3 = beta31*y1 + beta32*y2 + gam31*x1
")
```

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Union sentiment: using the sem package

Internally, **sem** expresses the model using "RAM" path notation (same as used by **specifyModel()**):

```
union.mod

##      Path      Parameter
## 1  x2 -> y1  gam12
## 2  y1 -> y2  beta21
## 3  x2 -> y2  gam22
## 4  y1 -> y3  beta31
## 5  y2 -> y3  beta32
## 6  x1 -> y3  gam31
## 7  x1 <-> x1 V[x1]
## 8  x1 <-> x2 C[x1,x2]
## 9  x2 <-> x2 V[x2]
## 10 y1 <-> y1 V[y1]
## 11 y2 <-> y2 V[y2]
## 12 y3 <-> y3 V[y3]
```

Fit the model using **sem()**:

```
union.sem <- sem(union.mod, union, N=173)
```

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Union sentiment: Goodness-of-fit statistics

The **summary()** method prints a collection of goodness-of-fit statistics:

```
opt <- options(fit.indices = c("GFI", "AGFI", "RMSEA", "NNFI",
  "CFI", "AIC", "BIC"))
summary(union.sem)
```

```
##
## Model Chisquare = 1.25 Df = 3 Pr(>Chisq) = 0.741
## Goodness-of-fit index = 0.997
## Adjusted goodness-of-fit index = 0.986
## RMSEA index = 0 90% CI: (NA, 0.0904)
## Tucker-Lewis NNFI = 1.0311
## Bentler CFI = 1
## AIC = 25.3
## BIC = -14.2
##
## ...
##
## R-square for Endogenous Variables
## y1 y2 y3
## 0.113 0.230 0.390
##
## ...
```

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Union sentiment: Parameter estimates

```
## Parameter Estimates
##      Estimate Std Error z value Pr(>|z|)
## gam12    -0.0874   0.0187  -4.68  2.90e-06 y1 <--- x2
## beta21    -0.2846   0.0617  -4.61  3.99e-06 y2 <--- y1
## gam22     0.0579   0.0161   3.61  3.09e-04 y2 <--- x2
## beta31    -0.2177   0.0971  -2.24  2.50e-02 y3 <--- y1
## beta32     0.8497   0.1121   7.58  3.52e-14 y3 <--- y2
## gam31     0.8607   0.3398   2.53  1.13e-02 y3 <--- x1
## V[x1]     1.0210   0.1101   9.27  1.80e-20 x1 <--> x1
## C[x1, x2]  7.1390   1.2556   5.69  1.30e-08 x2 <--> x1
## V[x2]    215.6620  23.2554   9.27  1.80e-20 x2 <--> x2
## V[y1]    12.9612   1.3976   9.27  1.80e-20 y1 <--> y1
## V[y2]     8.4882   0.9153   9.27  1.80e-20 y2 <--> y2
## V[y3]    19.4542   2.0978   9.27  1.80e-20 y3 <--> y3
```

The fitted model is:

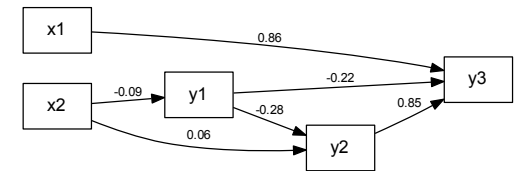
$$\begin{aligned}\hat{y}_1 &= -0.087x_2 \\ \hat{y}_2 &= -0.285y_1 + 0.058x_2 \\ \hat{y}_3 &= -0.218y_1 + 0.850y_2 + 0.861x_1\end{aligned}\quad \hat{\Psi} = \begin{bmatrix} 12.96 & & & \\ 0 & 8.49 & & \\ 0 & 0 & 19.45 & \\ & & & \end{bmatrix}$$

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Union sentiment: Path diagrams

- Path diagrams for a `sem()` model can be produced using `pathDiagram(model)`
- This uses the `graphvis` program (`dot`), that must be installed first (<http://www.graphviz.org/>)
- The latest version (`sem` 3.1-6) uses the `DiagrammeR` package instead
- Edges can be labeled with parameter names, values, or both

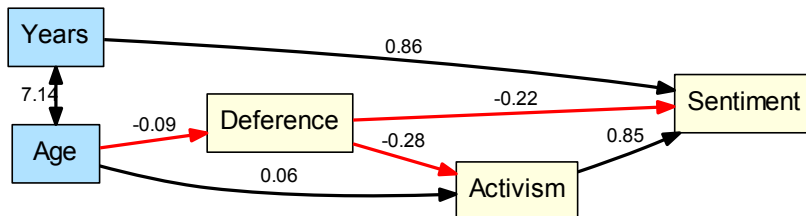
```
pathDiagram(union.sem,
  edge.labels="values",
  file="union-sem1",
  min.rank=c("x1", "x2"))
```



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Union sentiment: Path diagrams

- `dot` produces a text file describing the path diagram
- This can easily be (hand) edited to produce a nicer diagram
- Using color or linestyle for + vs. - edges facilitates interpretation



- The coefficients shown are **unstandardized**— on the scale of the variables
- Can also display **standardized** coefficients, easier to compare

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Fundamental hypothesis of CFA & SEM

- The covariance matrix (Σ) of the observed variables is a function of the parameters (θ) of the model

$$\Sigma = \Sigma(\theta)$$

- That is, if
 - Σ is the **population** covariance matrix of the observed variables, and
 - θ is a vector of all unique free parameters to be estimated,
 - then, $\Sigma(\theta)$ is the **model implied** or predicted covariance matrix, expressed in terms of the parameters.
- If the model is correct, and we knew the values of the parameters, then

$$\Sigma = \Sigma(\theta)$$

says that the population covariance matrix would be **exactly** reproduced by the model parameters

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Fundamental hypothesis of CFA & SEM

Example: Consider the simple linear regression model,

$$y_i = \gamma x_i + \zeta_i$$

If this model is true, then the variance and covariance of (y, x) are

$$\begin{aligned}\text{var}(y_i) &= \text{var}(\gamma x_i + \zeta_i) \\ &= \gamma^2 \text{var}(x_i) + \text{var}(\zeta_i) \\ \text{cov}(y_i, x_i) &= \gamma \text{var}(x_i)\end{aligned}$$

The hypothesis $\Sigma = \Sigma(\theta)$ means that Σ can be expressed in terms of the model-implied parameters, γ (regression slope), $\text{var}(\zeta)$ (error variance) and $\text{var}(x)$:

$$\Sigma \begin{pmatrix} y \\ x \end{pmatrix} = \begin{bmatrix} \text{var}(y) & \text{cov}(y, x) \\ \text{cov}(y, x) & \text{var}(x) \end{bmatrix} = \begin{bmatrix} \gamma^2 \text{var}(x) + \text{var}(\zeta) & \gamma \text{var}(x) \\ \gamma \text{var}(x) & \text{var}(x) \end{bmatrix} = \Sigma \begin{pmatrix} \gamma \\ \text{var}(\zeta) \\ \text{var}(x) \end{pmatrix}$$

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Fundamental hypothesis of CFA & SEM

This general hypothesis forms the basis for several important ideas in CFA and SEM

- Model **identification**: How to know if you can find a **unique** solution?
- Model **estimation**: How to fit a model to an observed covariance matrix (**S**)?
- **Goodness-of-fit** statistics: How to assess the discrepancy between **S** and $\Sigma(\theta)$?

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Model identification

- A model is **identified** if it is possible to find a **unique** estimate for each parameter
- A **non-identified** model has an **infinite** number of solutions— not too useful
- Such models may be made identified by:
 - Setting some parameters to **fixed** constants (like $\beta_{12} = 0$ or $\text{var}(\zeta_1) = 1$)
 - Constraining some parameters to be equal (like $\beta_{12} = \beta_{13}$)
- Identification can be stated as follows:
 - An unknown parameter θ is identified if it can be expressed as a function of one or more element of Σ
 - The whole model is identified if all parameters in θ are identified
- Complex models can often lead to identification problems, but there are a few simple helpful rules

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Model identification: t -rule and degrees of freedom

The simplest rule, the t -rule says:

- The number of unknown parameters to be estimated (t) cannot exceed the number of non-redundant variances and covariances of the observed variables
- This is a **necessary** condition for identification, but it is not **sufficient**

For path analysis models, let $P = p + q$ be the total number of endogenous (y) and exogenous (x) variables in Σ , and let t be the number of free parameters in θ . The t -rule is

$$P(P + 1)/2 \geq t$$

The difference gives the number of **degrees of freedom** for the model:

$$df = P(P + 1)/2 - t$$

- If $df < 0$, the model is **under-identified** (no unique solution)
- If $df = 0$, the model is **just-identified** (can't calculate goodness-of-fit)
- If $df > 0$, the model is **over-identified** (can calculate goodness-of-fit)

⇒ Useful SEM models should be **over-identified**!!

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Example: Union sentiment

For the Union sentiment model, the model parameters were:

$$\mathbf{B} = \begin{bmatrix} 0 & 0 & 0 \\ \beta_{21} & 0 & 0 \\ \beta_{31} & \beta_{32} & 0 \end{bmatrix} \quad \mathbf{\Gamma} = \begin{bmatrix} 0 & \gamma_{12} \\ 0 & \gamma_{22} \\ \gamma_{31} & 0 \end{bmatrix}$$

and

$$\mathbf{\Phi} = \begin{bmatrix} \text{var}(x_1) & & \\ \text{cov}(x_1, x_2) & \text{var}(x_2) & \\ & & \end{bmatrix} \quad \mathbf{\Psi} = \begin{bmatrix} \text{var}(\zeta_1) & & \\ 0 & \text{var}(\zeta_2) & \\ 0 & 0 & \text{var}(\zeta_2) \end{bmatrix}$$

Observed covariance matrix: $p = 3$ endogenous y s + $q = 2$ exogenous x s
 $\Rightarrow \Sigma_{5 \times 5}$ has $5 \times 6/2 = 15$ variances and covariances.

12 free parameters in the model:

- 6 regression coefficients (3 non-zero in \mathbf{B} , 3 non-zero in $\mathbf{\Gamma}$)
- 3 variances/covariances in $\mathbf{\Phi}$
- 3 residual variances in diagonal of $\mathbf{\Psi}$

The model $df = 15 - 12 = 3 > 0$, so this model is **over-identified**

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\mathbf{B} rules: $\mathbf{B} = 0$

Another simple rule applies if no endogenous y variable affects any other endogenous variable, so $\mathbf{B} = 0$

For example:

$$\begin{aligned} y_1 &= \gamma_{11}x_1 + \gamma_{12}x_2 && + \zeta_1 \\ y_2 &= \gamma_{21}x_1 && + \gamma_{23}x_3 && + \zeta_2 \\ y_3 &= \gamma_{31}x_1 && + \gamma_{33}x_3 &+ \gamma_{34}x_4 &+ \zeta_3 \end{aligned}$$

- $\mathbf{B} = 0$ because no y appears on the RHS of an equation
- Such models are **always** identified
- This is a **sufficient**, but not a necessary condition
- Residuals ζ_i in such models need not be uncorrelated, i.e., $\mathbf{\Psi}$ can be non-diagonal ("seemingly unrelated regressions")

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\mathbf{B} rules: recursive rule

The **recursive rule** applies if

- the only free elements in \mathbf{B} are on its **lower** (or upper) triangle, and
- $\mathbf{\Psi}$ is **diagonal** (no correlations amongst residuals)
- This basically means that there are no reciprocal relations among the y s and no feedback loops
- This also is a sufficient condition for model identification.

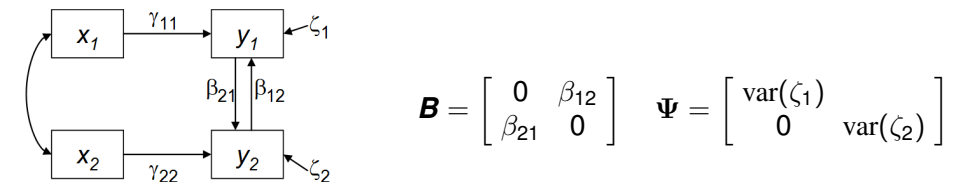
The union sentiment mode is recursive because \mathbf{B} is lower-triangular and $\mathbf{\Psi}$ is diagonal

$$\mathbf{B} = \begin{bmatrix} 0 & 0 & 0 \\ \beta_{21} & 0 & 0 \\ \beta_{31} & \beta_{32} & 0 \end{bmatrix} \quad \mathbf{\Psi} = \begin{bmatrix} \text{var}(\zeta_1) & & \\ 0 & \text{var}(\zeta_2) & \\ 0 & 0 & \text{var}(\zeta_2) \end{bmatrix}$$

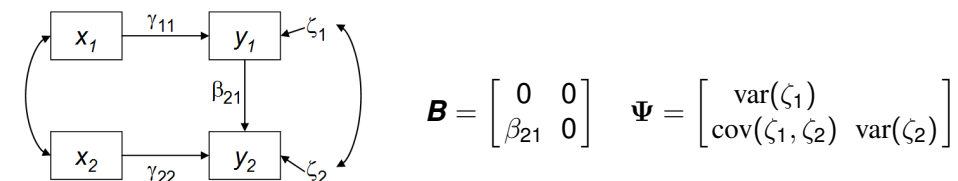
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\mathbf{B} rules: recursive rule

Non-recursive because \mathbf{B} is not lower-triangular:



Non-recursive because $\mathbf{\Gamma}$ is not diagonal:



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Model estimation

How to fit the model to your data?

- In ordinary regression analysis, the method of **least squares** is used to find values of the parameters (regression slopes) that minimize the sum of squared residuals, $\sum (y_i - \hat{y}_i)^2$.
 - This is fitting the model to the **individual observations**
- In contrast, SEM methods find parameter estimates that fit the model to the observed **covariance** matrix, \mathbf{S} .
- They are designed to minimize a function of the **residual covariances**, $\mathbf{S} - \Sigma_\theta$
 - If the model is correct, then $\Sigma_\theta = \Sigma$ and as $N \rightarrow \infty$, $\mathbf{S} = \Sigma$.
 - There is a variety of estimation methods for SEM, but all attempt to choose the values of parameters in θ to minimize a function $F(\bullet)$ of the difference between \mathbf{S} and Σ_θ

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Model estimation: Maximum likelihood

- ML estimates have optimal properties
 - **Unbiased**: $E(\hat{\theta}) = \theta$
 - Asymptotically **consistent**: as $N \rightarrow \infty$, $\hat{\theta} \rightarrow \theta$
 - Maximally **efficient**: smallest standard errors
- As $N \rightarrow \infty$, parameter estimates $\hat{\theta}_i$ are normally distributed, $\mathcal{N}(\hat{\theta}_i, \text{var}(\hat{\theta}_i))$, providing z (Wald) tests and confidence intervals

$$z = \frac{\hat{\theta}}{\text{s.e.}(\hat{\theta})} \quad CI_{1-\alpha} : \hat{\theta} \pm z_{1-\alpha/2} \text{se}(\hat{\theta})$$

- As $N \rightarrow \infty$, the value $(N - 1)F_{ML}$ has a χ^2 distribution with $df = P(P + 1)/2 - t$ degrees of freedom, giving an **overall test** of model fit.

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Model estimation: Maximum likelihood

- Maximum likelihood estimation is designed to maximize the likelihood (“probability”) of obtaining the observed data (Σ) over all choices of parameters (θ) in the model

$$\mathcal{L} = \Pr(\text{data} \mid \text{model}) = \Pr(\mathbf{S} \mid \Sigma_\theta)$$

- This assumes that the observed data are **multivariate normally** distributed
- ML estimation is equivalent to **minimizing** the following function:

$$F_{ML} = \log |\Sigma_\theta| - \log |\mathbf{S}| + \text{tr}(\mathbf{S}\Sigma_\theta^{-1}) - p$$

- All SEM software obtains some initial estimates (“start values”) and uses an iterative algorithm to minimize F_{ML}

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Model fit

- SEM provides R^2 values for each endogenous variable — the same as in **separate regressions** for each equation

```
## R-square for Endogenous Variables
##      y1      y2      y3
## 0.113 0.230 0.390
```

- More importantly, it provides **overall measures** of fit for the **entire model**.
- The model for union sentiment fits very well, even though the R^2 s are rather modest

```
## Model Chisquare = 1.25   Df = 3   Pr(>Chisq) = 0.741
## Goodness-of-fit index = 0.997
## Adjusted goodness-of-fit index = 0.986
## RMSEA index = 0      90% CI: (NA, 0.0904)
## Bentler CFI = 1
## AIC = 25.3
## BIC = -14.2
```

- A **just-identified** model will always fit perfectly— but that doesn’t mean it is a good model: there might be unnecessary or trivial parameters.
- An **over-identified** model that fits badly might have too many fixed or constrained parameters

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Model fit: χ^2 test

- The fitting function $F(\mathbf{S}, \hat{\Sigma})$ used to minimize the discrepancy between \mathbf{S} and the model estimate $\hat{\Sigma} = \Sigma(\hat{\theta})$ gives a **chi-square** test of model fit
- If the model is correct, then the minimized value, F_{min} , has an asymptotic chi-square distribution,

$$X^2 = (N - 1)F_{min} \sim \chi^2_{df}$$

with $df = P(P + 1)/2 - t$ degrees of freedom

- This gives a test of the hypothesis that the model fits the data

$$H_0 : \Sigma = \Sigma(\theta)$$

- a **large** (significant) X^2 indicates that the model **does not fit** the data.

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Model fit: χ^2 test— problems

- The test statistic, $X^2 = (N - 1)F_{min}$ is a function of sample size.
- With large N , trivial discrepancies will give a significant chi-square
- Worse, it tests an unrealistic hypothesis that the model fits **perfectly**
 - the specified model is **exactly** correct in all details
 - any lack-of-fit is due only to sampling error
 - it relies on asymptotic theory ($X^2 \sim \chi^2$ as $N \rightarrow \infty$) and an assumption of multivariate normality
- Another problem is **parsimony**— a model with additional free parameters will always fit better, but smaller models are simpler to interpret
- If you fit several **nested** models, $M_1 \supset M_2 \supset M_3 \dots$, chi-square tests for the **difference** between models are less affected by these problems

$$\Delta X^2 = X^2(M_1) - X^2(M_2) \sim \chi^2 \text{ with } df = df_1 - df_2$$

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Model fit: RMSEA

The measure of root mean square error of approximation (RMSEA) attempts to solve these problems (Browne & Cudeck, 1993)

$$RMSEA = \sqrt{\frac{X^2 - df}{(N - 1)df}}$$

- Relatively insensitive to sample size
- Parsimony adjusted— denominator adjusts for greater df
- Common labels for RMSEA values:

RMSEA	interpretation
0	perfect fit
$\leq .05$	close fit
.05 – .08	acceptable fit
.08 – .10	mediocre fit
$> .10$	poor fit

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Model fit: RMSEA

In addition, the RMSEA statistic has known sampling distribution properties (McCallum et al., 1996). This means that:

- You can calculate confidence intervals for RMSEA
- It allows to test a null hypothesis of “close fit” or “poor fit”, rather than “perfect fit”

$$H_0 : RMSEA < 0.05$$

$$H_0 : RMSEA > 0.10$$

- It allows for **power analysis** to find the sample size (N) required to reject a hypothesis of “close fit” ($RMSEA \leq 0.05$)

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Incremental fit indices

- Creating new indices of goodness-of-fit for CFA/SEM models was a “growth industry” for many years— there are many possibilities
- Incremental fit indices compare the existing model with a **null** or **baseline** model
 - The **null** model, M_0 assumes all variables are uncorrelated— the worst possible model.
 - Incremental fit indices compare the X_M^2 for model M with X_0^2 for the null model
 - All of these are designed to range from 0 to 1, with larger values (e.g., > 0.95) indicating better fit.
 - The generic idea is to calculate an R^2 -like statistic, of the form

$$\frac{f(\text{null model}) - f(\text{my model})}{f(\text{null model}) - f(\text{best model})}$$

for some function $f(\bullet)$ of X^2 and df , and where the “best” model fits perfectly.

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Information criteria: AIC, BIC

- Other widely used criteria, particularly when you have fit a **collection** of potential models are the “information criteria”, **AIC** and **BIC**
- Unlike the likelihood ratio tests these can be used to compare **non-nested** models
- Each of these uses a penalty for model complexity; BIC expresses a greater preference for simpler models as the sample size increases.

$$AIC = X^2 - 2df$$

$$BIC = X^2 - \log(N)df$$

- Smaller is better

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Incremental fit indices

Parsimony-adjusted indices also adjust for model df

- Bentler’s comparative fit index (CFI) is often widely used

$$CFI = 1 - \frac{X_M^2 - df_M}{X_0^2 - df_0}$$

- Tucker-Lewis Index (TLI), also called “non-normed fit index” (NNFI) are also popularly reported

$$TLI \equiv NNFI = \frac{X_0^2/df_0 - X_M^2/df_M}{X_0^2/df_0 - 1}$$

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Model modification

What to do when your model fits badly?

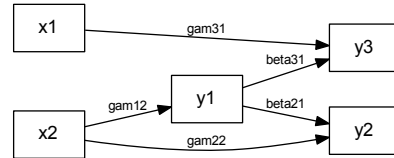
- First, note that a model might fit badly due to **data problems**:
 - outliers, missing data problems
 - non-normality (highly skewed, excessive kurtosis)
 - non-linearity, omitted interactions, ...
- Otherwise, bad model fit usually indicates that some important paths have been omitted, so some variances or covariances in **S** are poorly reproduced by the model
 - Some regression effects among (**x**, **y**) omitted (fixed to 0)?
 - Covariances among exogenous variables omitted? (**all** should be included)
 - Covariances among residuals might need to be included as **free** parameters
- Actions:
 - Examine **residuals**, **S** – $\Sigma(\hat{\theta})$ to see which variances/covariances are badly fit
 - **Modification indices** provide a way to test the impact of freeing each fixed parameter

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Example: Union sentiment

To illustrate, consider what would have happened if we omitted the important path of y_3 (sentiment) on y_2 (activism) in the Union sentiment example

```
mod.bad <- specifyEquations(covs="x1, x2", text='
y1 = gam12*x2
y2 = beta21*y1 + gam22*x2
y3 = beta31*y1 +      gam31*x1
')
```



Fit the model:

```
union.sem.bad <- sem(mod.bad, union, N=173)
union.sem.bad

##
## Model Chi-square = 50.235 Df = 4
##
##      gam12      beta21      gam22      beta31      gam31      V[x1]
## -0.087438 -0.284563  0.057938 -0.509024  1.286631  1.021000
## C[x1,x2]      V[x2]      V[y1]      V[y2]      V[y3]
## 7.139000 215.662000 12.961186  8.488216 25.863934
##
## Iterations = 0
```

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As expected, this model fits very badly

```
summary(union.sem.bad, fit.indices=c("RMSEA", "NNFI", "CFI"))

##
## Model Chi-square = 50.235 Df = 4 Pr(>ChiSq) = 3.2251e-10
## RMSEA index = 0.25923 90% CI: (0.19808, 0.32556)
## Tucker-Lewis NNFI = 0.38328
## Bentler CFI = 0.75331
##
## Normalized Residuals
## Min. 1st Qu. Median Mean 3rd Qu. Max.
## -0.159 0.000 0.000 0.594 0.330 5.247
##
## R-square for Endogenous Variables
## y1 y2 y3
## 0.1129 0.2295 0.1957
##
## ...
```

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Normalized residuals show the differences $\mathbf{S} - \Sigma(\hat{\theta})$ as approximate z-scores, so values outside of ± 2 can be considered significantly large.

```
round(normalizedResiduals(union.sem.bad), 3)
```

```
##      y1      y2      y3      x1      x2
## y1 0.000 0.000 0.103 0.477 0.000
## y2 0.000 0.000 5.246 0.330 0.000
## y3 0.103 5.246 -0.054 -0.159 1.454
## x1 0.477 0.330 -0.159 0.000 0.000
## x2 0.000 0.000 1.454 0.000 0.000
```

- This points to the one very large residual for the $y_2 \rightarrow y_3$ (or $y_3 \rightarrow y_2$) path
- In this example Union sentiment (y_3) is the main outcome, so it would make sense here to free the $y_2 \rightarrow y_3$ path

Modification indices

- Modification indices provide test statistics for **fixed** parameters
- The statistics estimate the decrease in X^2 if each fixed parameter was allowed to be freely estimated
- These are $\chi^2(1)$ values, so values > 4 can be considered “significantly” large.

```
modIndices(union.sem.bad)
```

```
##
## 5 largest modification indices, A matrix (regression coefficients):
## y3<-y2 y2<-y3 x2<-y3 y3<-x2 y1<-y3
## 42.071 38.217 4.240 3.947 3.763
##
## 5 largest modification indices, P matrix (variances/covariances):
## y3<->y2 y3<->y1 x2<->y3 x1<->y3 x1<->y2
## 38.3362 3.9468 3.9468 3.9468 0.4114
```

Once again, we see large values associated with the $y_2 \rightarrow y_3$ path

Modification indices: Caveats

- Using modification indices to improve model fit is called **specification search**
- This is often deprecated, unless there are good substantive reasons for introducing new free parameters
 - New paths or covariances in the model should make sense theoretically
 - Large modification indices could just reflect sample-specific effects

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Summary

Summary II

- **Path diagrams** provide a convenient way to portray or visualize a SEM
 - Direct translation from/to a system of linear equations
 - Some software (AMOS graphics) allows construction of the model via a path diagram
 - Most SEM software provides for output of models and results as path diagrams
- **Path analysis models** provide a basic introduction to SEM
 - No **latent** variables— only observed (“manifest”) ones
 - Does not allow for **errors of measurement** in observed variables
 - **exogenous** variables (x s)— only **predictors** in the linear equations
 - **endogenous** variables (y s)— a **dependent** variable in one or more equations
 - Error terms reflect **errors-in-equations**— unmodeled predictors, wrong functional form, etc.
- An important question in SEM models is **model identification**— can the parameters be uniquely estimated?
- Another important question is how to evaluate **model fit**?

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Summary I

- **Structural equation models** are an historical development of EFA and CFA methods and path analysis
 - EFA and CFA attempt to explain correlations among observed variables in terms of **latent variables** (“factors”)
 - EFA used factor rotation to obtain an interpretable solution
 - CFA imposes restrictions on a solution, and allows specific **hypothesis tests**
 - Higher-order CFA further generalized CFA to the ACOVS model
 - Meanwhile, path analysis developed methods for analyzing **systems of equations** together
 - The result, was SEM, in the form of the LISREL model

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